Contents

Preface *xi* Acknowledgments *xvii*

Part I Agent-Based Modeling and NetLogo Basics 1

1 Models, Agent-Based Models, and the Modeling Cycle 3

- 1.1 Introduction, Motivation, and Objectives 3
- 1.2 What Is a Model? 4
- 1.3 What Does the Modeling Cycle Involve? 7
- 1.4 What Is Agent-Based Modeling? How Is It Different? 10
- 1.5 Summary and Conclusions 12
- 1.6 Exercises 13

2 Getting Started with NetLogo 15

- 2.1 Introduction and Objectives 15
- 2.2 A Quick Tour of NetLogo 16
- 2.3 A Demonstration Program: Mushroom Hunt 18
- 2.4 Summary and Conclusions 29
- 2.5 Exercises 32

3 Describing and Formulating ABMs: The ODD Protocol 35

- 3.1 Introduction and Objectives 35
- 3.2 What Is ODD and Why Use It? 36
- 3.3 The ODD Protocol 37
- 3.4 Our First Example: Virtual Corridors of Butterflies 43
- 3.5 Summary and Conclusions 46
- 3.6 Exercises 47

4 Implementing a First Agent-Based Model 49

- 4.1 Introduction and Objectives 49
- 4.2 ODD and NetLogo 49

- 4.3 Butterfly Hilltopping: From ODD to NetLogo 50
- 4.4 Comments and the Full Program 57
- 4.5 Summary and Conclusions 60
- 4.6 Exercises 61
- 5 From Animations to Science 63
 - 5.1 Introduction and Objectives 63
 - 5.2 Observation of Corridors 64
 - 5.3 Analyzing the Model 69
 - 5.4 Time-Series Results: Adding Plots and File Output 69
 - 5.5 A Real Landscape 71
 - 5.6 Summary and Conclusions 74
 - 5.7 Exercises 75
- 6 Testing Your Program 77
 - 6.1 Introduction and Objectives 77
 - 6.2 Common Kinds of Errors 78
 - 6.3 Techniques for Debugging and Testing NetLogo Programs 81
 - 6.4 Documentation of Tests 91
 - 6.5 An Example and Exercise: The Culture Dissemination Model 92
 - 6.6 Summary and Conclusions 94
 - 6.7 Exercises 95

Part II Model Design Concepts 97

- 7 Introduction to Part II 99
 - 7.1 Objectives of Part II 99
 - 7.2 Overview of Part II 100
- 8 Emergence 103
 - 8.1 Introduction and Objectives 103
 - 8.2 A Model with Less Emergent Dynamics 104
 - 8.3 Simulation Experiments and BehaviorSpace 105
 - 8.4 A Model with Complex Emergent Dynamics 111
 - 8.5 Summary and Conclusions 116
 - 8.6 Exercises 116
- 9 Observation 119
 - 9.1 Introduction and Objectives 119
 - 9.2 Observing the Model via NetLogo's View 120
 - 9.3 Other Interface Displays 123
 - 9.4 File Output 124
 - 9.5 BehaviorSpace as an Output Writer 128
 - 9.6 Export Primitives and Menu Commands 128
 - 9.7 Summary and Conclusions 129
 - 9.8 Exercises 129
- 10 Sensing 131
 - 10.1 Introduction and Objectives 131
 - 10.2 Who Knows What: The Scope of Variables 132
 - 10.3 Using Variables of Other Objects 135
 - 10.4 Putting Sensing to Work: The Business Investor Model 136

- 10.5 Summary and Conclusions 145
- 10.6 Exercises 146

11 Adaptive Behavior and Objectives 149

- 11.1 Introduction and Objectives 149
- 11.2 Identifying and Optimizing Alternatives in NetLogo 150
- 11.3 Adaptive Behavior in the Business Investor Model 154
- 11.4 Nonoptimizing Adaptive Behavior: A Satisficing Example 155
- 11.5 The Objective Function 158
- 11.6 Summary and Conclusions 159
- 11.7 Exercises 160

12 Prediction 161

- 12.1 Introduction and Objectives 161
- 12.2 Example Effects of Prediction: The Business Investor Model's Time Horizon 162
- 12.3 Implementing and Analyzing Submodels 164
- 12.4 Analyzing the Investor Utility Function 167
- 12.5 Modeling Prediction Explicitly 169
- 12.6 Summary and Conclusions 170
- 12.7 Exercises 171

13 Interaction 173

- 13.1 Introduction and Objectives 173
- 13.2 Programming Interaction in NetLogo 174
- 13.3 The Telemarketer Model 175
- 13.4 The March of Progress: Global Interaction 180
- 13.5 Direct Interaction: Mergers in the Telemarketer Model 180
- 13.6 The Customers Fight Back: Remembering Who Called 182
- 13.7 Summary and Conclusions 185
- 13.8 Exercises 186

14 Scheduling 189

- 14.1 Introduction and Objectives 189
- 14.2 Modeling Time in NetLogo 190
- 14.3 Summary and Conclusions 198
- 14.4 Exercises 199

15 Stochasticity 201

- 15.1 Introduction and Objectives 201
- 15.2 Stochasticity in ABMs 202
- 15.3 Pseudorandom Number Generation in NetLogo 204
- 15.4 An Example Stochastic Process: Empirical Model of Behavior 210
- 15.5 Summary and Conclusions 211
- 15.6 Exercises 213

16 Collectives 215

- 16.1 Introduction and Objectives 215
- 16.2 What Are Collectives? 216
- 16.3 Modeling Collectives in NetLogo 216
- 16.4 Example: A Wild Dog Model with Packs 218
- 16.5 Summary and Conclusions 228
- 16.6 Exercises 229

Part III Pattern-Oriented Modeling 231

- 17 Introduction to Part III 233
 - 17.1 Toward Structurally Realistic Models 233
 - 17.2 Single and Multiple, Strong and Weak Patterns 234
 - 17.3 Overview of Part III 236
- 18 Patterns for Model Structure 239
 - 18.1 Introduction and Objectives 239
 - 18.2 Steps in POM to Design Model Structure 240
 - 18.3 Example: Modeling European Beech Forests 241
 - 18.4 Example: Management Accounting and Collusion 245
 - 18.5 Summary and Conclusions 246
 - 18.6 Exercises 247

19 Theory Development 249

- 19.1 Introduction and Objectives 249
- 19.2 Theory Development and Strong Inference in the Virtual Laboratory 250
- 19.3 Examples of Theory Development for ABMs 252
- 19.4 Exercise Example: Stay or Leave? 255
- 19.5 Summary and Conclusions 259
- 19.6 Exercises 260

20 Parameterization and Calibration 263

- 20.1 Introduction and Objectives 263
- 20.2 Parameterization of ABMs Is Different 264
- 20.3 Parameterizing Submodels 265
- 20.4 Calibration Concepts and Strategies 266
- 20.5 Example: Calibration of the Woodhoopoe Model 272
- 20.6 Summary and Conclusions 275
- 20.7 Exercises 276

Part IV Model Analysis 279

- 21 Introduction to Part IV 281
 - 21.1 Objectives of Part IV 281
 - 21.2 Overview of Part IV 282

22 Analyzing and Understanding ABMs 285

- 22.1 Introduction and Objectives 285
- 22.2 Example Analysis: The Segregation Model 286
- 22.3 Additional Heuristics for Understanding ABMs 291
- 22.4 Statistics for Understanding 295
- 22.5 Summary and Conclusions 296
- 22.6 Exercises 297

23 Sensitivity, Uncertainty, and Robustness Analysis 299

- 23.1 Introduction and Objectives 299
- 23.2 Sensitivity Analysis 301
- 23.3 Uncertainty Analysis 307
- 23.4 Robustness Analysis 312

- 23.5 Summary and Conclusions 313
- 23.6 Exercises 314

24 Where to Go from Here 317

- 24.1 Introduction and Objectives 317
- 24.2 Keeping Your Momentum: Reimplementation 318
- 24.3 Your First Model from Scratch 318
- 24.4 Modeling Agent Behavior 319
- 24.5 ABM Gadgets 320
- 24.6 NetLogo as a Platform for Large Models 321
- 24.7 An Odd Farewell 323

References 325 Index 333 Index of Programming Notes 339

Models, Agent-Based Models, and the Modeling Cycle

1.1 Introduction, Motivation, and Objectives

Why is it important to learn how to build and use agent-based models (ABMs) or "individualbased" models, as they are called in some fields? The short answer to this question is that we need ABMs to solve problems that traditional models and methods are too simple for. For example, An (2001) showed that a simple ABM could explain the previously misunderstood dynamics of a medical syndrome that kills many people. Ecologists have learned that traditional models of the basic relations between predator and prey populations are unrealistic because they ignore individual behaviors that ABMs can represent (Abrams 1993; Railsback and Harvey 2013). In perhaps the most prominent example, the 2008 global financial crisis has been attributed in part to policy models that simplify away the essential complexities that ABMs can address (Buchanan 2009).

Let's now look closely at one real model and the difference it has made.

1.1.1 A Motivational Example: Rabies Control in Europe

Rabies is a viral disease that kills great numbers of wild mammals and can spread to domestic animals and people. In Europe, rabies is transmitted mainly by red foxes. When an outbreak starts in a previously rabies-free region, it spreads in "traveling waves": alternating areas of high and low infection rates.

Rabies can be eradicated from large areas, and new outbreaks can be controlled, by immunizing foxes: European governments have eradicated rabies from central Europe by manufacturing rabies vaccine, injecting it into baits, and spreading the baits from aircraft. However, this program is extremely expensive and works only if new outbreaks are detected and contained. Key to its cost-effectiveness are these questions: What percentage of wild foxes need to be vaccinated to eliminate rabies from an area, and what is the best strategy for responding to outbreaks?

Models have long been applied to such epidemiological problems, for wildlife as well as people. Classical differential equation models of the European rabies problem predicted that

70% of the fox population must be vaccinated to eliminate rabies. Managers planned to respond to new outbreaks using a "belt vaccination" strategy (which has worked well for other epidemics, including smallpox): not vaccinating the outbreak location itself but a belt around it, the width of which was usually determined by the limited emergency supply of vaccine. The 70% vaccination strategy did succeed, but the rabies problem has several characteristics suggesting that an agent-based modeling approach could make important contributions: the spread of rabies has important patterns in space as well as time, and is driven by individual behavior (in this case, the use of stationary territories by most foxes but long-distance migration by young foxes). Hence, Florian Jeltsch and colleagues developed a simple ABM that represented fox families in stationary home ranges and migration of young foxes (Jeltsch et al. 1997). This model accurately simulated the spread of rabies over both space and time.

Dirk Eisinger and Hans-Hermann Thulke then modified the ABM specifically to evaluate how the distribution of vaccination baits over space affects rabies control (Thulke and Eisinger 2008, Eisinger and Thulke 2008, Eisinger et al. 2005). Their ABM indicated that eradication could be achieved with a vaccination rate much lower than 70%, a result that could save millions of euros and was confirmed by the few case studies where actual vaccination coverage was monitored. The reason for the lower vaccination rate predicted by the ABM is that the "wave" spread of rabies emerges from local infectious contacts that actually facilitate eradication. The ABM of Eisinger and Thulke also indicated that the belt vaccination strategy for outbreaks would fail more often than an alternative: compact treatment of a circle around the initial outbreak. Because the ABM had reproduced many characteristics of real outbreaks and its predictions were easy to understand, rabies managers accepted this result and began successfully—to apply the compact vaccination strategy.

The rabies example shows that agent-based modeling can find new, better solutions to many problems important to our environment, health, and economy—and has already done so. The common feature of these problems is that they occur in systems composed of autonomous "agents" that interact with each other and their environment, differ from each other and over space and time, and have behaviors that are often very important to how the system works.

1.1.2 Objectives of Chapter 1

This chapter is your introduction to modeling and agent-based modeling. We get started by clarifying some basic ideas about modeling. These lessons may seem trivial at first, but they are in fact the very foundation for everything else in this course. Learning objectives for this chapter are to develop a firm understanding of

- What models are, and what modeling is—why do we build models anyway?
- What the modeling cycle involves—what is the iterative process of designing, implementing, and analyzing models and using them to solve scientific problems?
- What agent-based models are—how are ABMs different from other kinds of models, and why would you use them?

1.2 What Is a Model?

A model is a purposeful representation of some real system (Starfield et al. 1990). We build and use models to solve problems or answer questions about a system or a class of systems. In science, we usually want to understand how things work, explain patterns that we have observed, and predict a system's behavior in response to some change. Real systems often are

too complex or develop too slowly to be analyzed using experiments. For example, it would be extremely difficult and slow to understand how cities grow and land uses change just with experiments. Therefore, we try to formulate a simplified representation of the system using equations or a computer program that we can then manipulate and experiment on. (To formulate a model means to design its assumptions and algorithms.)

But there are many ways of representing a real system (a city or landscape, for example) in a simplified way. How can we know which aspects of the real system to include in the model and which to ignore? To answer this question, the model's purpose is decisive. The question we want to answer with the model serves as a filter: all those aspects of the real system considered irrelevant or insufficiently important for answering *this* question are filtered out. They are ignored in the model, or represented only in a very simplified way.

Let us consider a simple, but not trivial, example: Did you ever search for mushrooms in a forest? Did you ask yourself what the best search strategy might be? If you are a mushroom expert, you would know how to recognize good mushroom habitat, but let us assume you are a neophyte. And even the mushroom expert needs a smaller-scale search strategy because mushrooms are so hard to see—you often almost step on them before seeing them.

You might think of several intuitive strategies, such as scanning an area in wide sweeps but, upon finding a mushroom, turning to smaller-scale sweeps because you know that mushrooms occur in clusters. But what does "large" and "small" and "sweeps" mean, and how long should you search in smaller sweeps until you turn back to larger ones?

Many animal species face similar problems, so it is likely that evolution has equipped them with good adaptive search strategies. (The same is likely true of human organizations searching for prizes such as profit and peace with neighbors.) Albatross, for example, behave like mush-room hunters: they alternate more or less linear long-distance movements with small-scale searching (figure 1.1).

The common feature of the mushroom hunter and the albatross is that their sensing radius is limited—they can only detect what they seek when they are close to it—so they must move.



Figure 1.1

Flight path of a female wandering albatross (*Diomedea exulans*) feeding in the southern Indian ocean. The flight begins and ends at a breeding colony (indicated by the star) in the Crozet Islands. Data recorded by H. Weimerskirch and colleagues for studies of adaptive search behavior in albatross (e.g., Weimerskirch et al. 2007).

And often the items searched for are not distributed randomly or regularly but in clusters, so search behavior should be adaptive: it should change once an item is found.

Why would we want to develop a model of this problem? Because even for this simple problem we are not able to develop quantitative mental models. Intuitively, we find a search strategy that works quite well, but then we see others who use different strategies and find more mushrooms. Are they just luckier, or are their strategies better?

Now we understand that we need a clearly defined purpose before we can formulate a model. Imagine that someone simply said to you, "Please, model mushroom hunting in the forest." What should you focus on? On different mushroom species, different forests, identification of good and bad habitats, effects of hunting on mushroom populations, etc.? However, with the purpose "What search strategy maximizes the number of mushrooms found in a certain time?" we know that

- We can ignore trees and vegetation; we only need to take into account that mushrooms are distributed in clusters. Also, we can ignore any other heterogeneity in the forest, such as topography or soil type—they might affect searching a little, but not enough to change the general answer to our question.
- It will be sufficient to represent the mushroom hunter in a very simplified way: just a moving "point" that has a certain sensing radius and keeps track of how many mushrooms it has found and perhaps how long it has been since it found the last one.

So now we can formulate a model that includes clusters of items and an individual "agent" that searches for the items in the model world. If it finds a search item, it switches to smaller-scale movement, but if the time since it found the last item exceeds a threshold, it switches back to more straight movement to increase its chances of detecting another cluster of items. If we assume that the ability to detect items does not change with movement speed, we can even ignore speed.

Figure 1.2 shows an example run of such a model, our simple Mushroom Hunt model. In chapter 2 you will start learning NetLogo, the software platform we use in this book, by programming this little model.

This searching problem is so simple that we have good idea of what processes and behaviors are important for modeling it. But how in general can we know whether certain factors



Figure 1.2 Path of a model agent searching for items that are distributed in clusters.

are important with regard to the question addressed with a model? The answer is we can't! That is exactly why we have to formulate, implement (program in the computer), and analyze a model, because then we can use mathematics and computer logic to rigorously explore the consequences of our simplifying assumptions.

Our first formulation of a model must be based on our preliminary understanding of how the system works, what the important elements and processes are, and so on. These preliminary ideas might be based on empirical knowledge of the system's behavior, on earlier models addressing similar questions, on theory, or just on . . . imagination (as in the mushroom hunting example). However, if we have no idea whatsoever how the system works, we cannot formulate a model! For example, even though scientists are happy to model almost everything, so far there seems to be no explicit model of human consciousness, simply because we have no clue what consciousness really is and how it emerges.

Because the assumptions in the first version of a model are experimental, we have to test whether they are appropriate and useful. For this, we need criteria for whether the model can be considered a good representation of the real system. These criteria are based on patterns or regularities that let us identify and characterize the real system in the first place. Stock market models, for example, should produce the kinds of volatility and trends in prices we see in real markets. Often we find that the first version of a model is too simple, lacks important processes and structures, or is simply inconsistent. We thus go back and revise our simplifying assumptions.

1.3 What Does the Modeling Cycle Involve?

When thinking about a model of a mushroom hunter (or albatross), we intuitively went through a series of tasks. Scientific modeling means going through these tasks in a systematic way and using mathematics and computer algorithms to rigorously determine the consequences of the simplifying assumptions that make up our models.

Being scientific always means iterating through the tasks of modeling several times, because our first models can always be improved in some way: they are too simple or too complex, or they make us realize that we are asking the wrong questions. It is therefore useful to view modeling as iterating through the "modeling cycle" (figure 1.3). *Iterating* does not mean that we always go through the full cycle; rather, we often go through smaller loops, for example, between problem formulation and verbal formulation of the model. The modeling cycle consists of the following tasks:

 Formulate the question. We need to start with a very clear research question because this question then serves as the primary compass and filter for designing a model. Often, formulating a clear and productive question is by itself a major task because a clear question requires a clear focus. For complex systems, getting focused can be difficult. Very often, even our questions are only experimental and later we might need to reformulate the question, perhaps because it turns out not to be clear enough, or too simple, or too complex.

The question in our Mushroom Hunt model is, What search strategy maximizes the rate of finding items if they are distributed in clusters?

2. Assemble hypotheses for essential processes and structures. Agent-based modeling is "naive" (DeAngelis et al. 1994) in the sense that we are not trying to aggregate agents and what they are doing in some abstract variables like abundance, biomass, overall wealth, demographic rates, or nutrient fluxes. Instead, we naively and directly represent the agents and their behavior. We create these agents, put them in a virtual environment, and then



let the virtual world run and see what we can learn from it. (It is important, though, to ask ourselves: Is it possible to answer our question using a more aggregated and thus simpler model?)

Usually, we have to formulate many hypotheses for what processes and structures are essential to the question or problem we address. We can start top-down and ask ourselves questions such as, What factors have a strong influence on the phenomena of interest? Are these factors independent or interacting? Are they affected by other important factors? We might draw so-called influence diagrams, or flow charts, or just caricatures of our system and question. But whatever technique we prefer, this task has to combine our existing knowledge and understanding with a brainstorming phase in which we wildly hypothesize, followed by, most importantly, a simplification phase.

We have to force ourselves to simplify as much as we can, or even more. The modeling cycle must be started with the most simple model possible, because we want to develop understanding gradually, while iterating through the cycle. A common mistake of beginners is to throw too much into the first model version—usually arguing that all these factors are well known and can't possibly be ignored. The modeling expert's answer to this is, yes, you might be right, but—let us focus on the absolute minimum number of factors first. Put all the other elements that you think might need to be in the model on your "wish list" and check their importance later.

The reason for this advice is this: just our preliminary understanding of a system is not sufficient for deciding whether things are more or less important for a model. It is the very purpose of the model to teach us what is important. So it is wise to have a model implemented as soon as possible, even if it is ridiculously simple. The simpler the model is, the easier it is to implement and analyze, and the sooner we are productive. The real productive phase in a modeling project starts when we get the modeling cycle running: assumptions—implementation—model output—analyses—interpretation—revised assumptions, and so on.

It is difficult to formalize this task of the modeling cycle. One important help is heuristics for modeling: rules of thumb that are often, but not always, useful for designing models. We point out these heuristics throughout this book; use the index to find them. Compilations of modeling heuristics can be found in Starfield et al. (1990) and Grimm and Railsback (2005, chapter 2). And—in part III of this book we present *pattern-oriented modeling*, a very important strategy for formalizing both this and the next step in the modeling cycle.

For the Mushroom Hunt model, we assume that the essential process is switching between relatively straight large-scale "scanning" movement and small-scale searching, depending on how long it has been since the hunter last found an item.

3. *Choose scales, entities, state variables, processes, and parameters.* Once we choose some simplifying assumptions and hypotheses to represent our system of interest, it is time to sit down and think through our model in detail. We thus produce a written formulation of the model. Producing and updating this formulation is essential for the entire modeling process, including delivery to our "clients" (our thesis committee, journal reviewers, research sponsors, etc.). In chapter 3, we will start using a very helpful protocol for doing this.

This step, for the Mushroom Hunt model, includes specifying how the space that hunters move through is represented (as square grids with size equal to the area the hunter can search in one time step), what kinds of objects are in the model (one hunter and the items it searches for), the state variables or characteristics of the hunter (the time it has hunted and the number of items it has found, and the time since last finding an item), and exactly how the hunter searches. (Full details are provided when we implement the model in chapter 2.)

4. *Implement the model.* This is the most technical part of the modeling cycle, where we use mathematics and computer programs to translate our verbal model description into an "animated" object (Lotka 1925). Why animated? Because, in a way, the implemented model has its own independent dynamics (or "life"), driven by the internal logic of the model. Our assumptions may be wrong or incomplete, but the implementation itself is—barring software mistakes—always right: it allows us to explore, in a logical and rigorous way, the consequences of our assumptions and see whether our initial model looks useful.

This task is often the most daunting one for neophytes in modeling, because they usually have no training in how to build software. Thus, our claim that the implementation is always "right" might sound ironic to beginners. They might struggle for months to get the implementation right—but only if they don't take advantage of existing software platforms for agent-based modeling. With the platform that we use in this book, NetLogo, you can often implement simple ABMs within a day or two, including the time to test your code and show that it is accurate. So please don't panic!

5. Analyze, test, and revise the model. While new modelers might think that designing a model and implementing it on the computer takes the most work, this task—analyzing a model and learning from it—is the most time-consuming and demanding one. With tools like NetLogo, you will learn to quickly implement your own ABMs. But doing science with ABMs requires much more. Much of this book will be devoted to this task: How can we learn from our models? In particular, we will try to put forward the research program of "individual-based ecology" (Grimm and Railsback 2005) and apply it to other sciences. This program is dedicated to learning about the real world: we do not just want to see what happens when we create some agents and make up their behaviors—we want to see what agent behaviors can explain and predict important characteristics of real systems. To answer the mushroom hunting question, we could analyze the model by trying

a variety of search algorithms and parameter values to see which produce the highest rate of finding items.

6. Communicate the model. Here, "communicate" means to publish or otherwise transfer the knowledge produced so far to clients, other scientists, and perhaps even the public. Of course, many other kinds of communication take place throughout the modeling cycle. One very important benefit of this task is that it enforces discipline on the modeling cycle by making us stop the other tasks long enough to thoroughly document what we have done and learned so far, and to think and get feedback on what we should do next.

1.4 What Is Agent-Based Modeling? How Is It Different?

Historically, the complexity of scientific models was often limited by mathematical tractability: when differential calculus was the only approach we had for modeling, we had to keep models simple enough to "solve" mathematically and so, unfortunately, we were often limited to modeling quite simple problems—or forced to address complex problems with models that were too simple.

With computer simulation, the limitation of mathematical tractability is removed so we can start addressing problems that require models that are less simplified and include more characteristics of the real systems. ABMs are less simplified in one specific and important way: they represent a system's individual components and their behaviors. Instead of describing a system only with variables representing the state of the whole system, we model its individual agents. ABMs are thus models where individuals or agents are described as unique and autonomous entities that usually interact with each other and their environment locally. Agents may be organisms, humans, businesses, institutions, and any other entity that pursues a certain goal. Being unique implies that agents usually are different from each other in characteristics such as size, location, resource reserves, and history. Interacting locally means that agents usually do not interact with all other agents but only with their neighbors—in geographic space or in some other kind of "space" such as a network. Being autonomous implies that agents act independently of each other and pursue their own objectives. Organisms strive to survive and reproduce; traders in the stock market try to make money; businesses have goals such as meeting profit targets and staying in business; regulatory authorities want to enforce laws and provide public well-being. Agents therefore use *adaptive behavior*: they adjust their behavior to the current states of themselves, of other agents, and of their environment.

Using ABMs lets us address problems that concern *emergence*: system dynamics that arise from how the system's individual components interact with and respond to each other and their environment. Hence, with ABMs we can study questions of how a system's behavior arises from, and is linked to, the characteristics and behaviors of its individual components.

ABMs are useful for problems of emergence because they are *across-level* models. Traditionally, some scientists have studied only systems, modeling them using approaches such as differential equations that represent how the whole system changes. Other scientists have studied only what we call agents: how plants and animals, people, organizations, etc. change and adapt to external conditions. ABMs are different because they are concerned with two (and sometimes more) levels and their interactions: we use them to both look at what happens to the *system* because of what its *individuals* do and what happens to the *individuals* because of what the *system* does. So throughout this course there will be a focus on modeling the behavior of agents and, at the same time, observing and understanding the behavior of the system made up by the agents.

ABMs are also often different from traditional models by being "unsimplified" in other ways, such as representing how individuals, and the environmental variables that affect them, vary over space, time, or other dimensions. ABMs often include processes that we know to be important but that are too complex to include in simpler models.

What kinds of problems can we address with ABMs? Every year more and more important problems are addressed with ABMs because they demand across-level approaches and are too complex to address without models or with only simple models. Here are some examples:

- What factors caused the housing market collapse of 2008, and what policy changes could prevent a recurrence (Gilbert et al. 2009, Geanakoplos 2012)?
- What causes the complex and seemingly unpredictable dynamics of a stock market? Are market fluctuations caused by dynamic behavior of traders, variation in stock value, or simply the market's trading rules (LeBaron 2001, Duffy 2006)?
- How can we manage tropical forests in a sustainable way, maintaining both economic uses and biodiversity levels critical for forests' stability properties (Huth et al. 2004, Bohn and Huth 2017)?
- How do shorebird populations respond to loss or alteration of the mudflats they feed in, and how can the effects be mitigated cost-effectively (Goss-Custard et al. 2006, Garcia et al. 2016)?
- How is development and maintenance of human tissue regulated by signals from the genome and the extracellular environment and by cellular behaviors such as migration, proliferation, differentiation, and cell death? How do diseases result from abnormalities in this system (Peirce et al. 2004, An 2015, Martin et al. 2015)?
- How do pharmaceuticals interact with human organs and within-organ processes to produce both benefits (Hunt et al. 2013) and undesirable side effects (Smith et al. 2016)?
- What drives patterns of land use change during urban sprawl, and how are they affected by the physical environment and by management policies (Parker et al. 2003, Brown et al. 2004, Groeneveld et al. 2017)?

The ability of ABMs to address complex, multilevel problems comes at a cost, of course. Traditional modeling requires mathematical skills, especially differential calculus and statistics. But to use simulation modeling we need additional skills. This course is designed to give you three very important skills for using ABMs:

- A new "language" for thinking about and describing models. Because we cannot define ABMs concisely or accurately in the languages of differential equations or statistics, we need a standard set of concepts (e.g., emergence, adaptive behavior, interaction, sensing) that describe the important elements of ABMs.
- The software skills to implement models on computers and to observe, test, control, and analyze the models. Producing useful software is more complex for ABMs than for most other kinds of models.
- Strategies for designing and analyzing models. There is almost no limit to how complex a computer simulation model can be, but if a model is too complex it quickly becomes too hard to parameterize, validate, or analyze. We need a way to determine what entities, variables, and processes should and should not be in a model, and we need methods for analyzing a model, after it is built, to learn about the real system.

Full-fledged ABMs assume that agents are different from each other; that they interact with only some, not all, other agents; that they change over time; that they can have different "life cycles" or stages they progress through, possibly including birth and death; and that they make

autonomous adaptive decisions to pursue their objectives. However, as with any model assumption, assuming that these individual-level characteristics are important is experimental. It might turn out that for many questions we do not explicitly need all, or even any, of these characteristics. And in fact full-fledged ABMs are quite rare. In ecology, for example, many useful ABMs include only one individual-level characteristic: local interactions. Thus, although ABMs are defined by the assumption that agents are represented in some way, we still have to make many choices about what type of agents to represent and in what detail.

Because most model assumptions are experimental, we need to test our model: we must implement the model and analyze its assumptions. For the complex systems we usually deal with in science, just thinking is not sufficient to rigorously deduce the consequences of our simplifying assumptions: we have to let the computer show us what happens. We thus have to iterate through the modeling cycle.

1.5 Summary and Conclusions

Agent-based modeling is no longer a completely new approach, but it still offers many exciting new ways to look at old problems and lets us study many new problems. In fact, the use of ABMs is even more exciting now that the approach has matured: the worst mistakes have been made and corrected, agent-based approaches are no longer considered radical and suspicious, and we have convenient tools for building models. People like you are positioned to take advantage of what the pioneers have learned and the tools they have built, and to get directly to work on interesting problems.

In this first chapter our goal is to provide some extremely fundamental and important ideas about modeling and agent-based modeling. Whenever you find yourself frustrated with either your own model or someone else's, in "big-picture" ways (What exactly does this model do? Is it a good model or not? Should I add this or that process to my model? Is my model "done"?), it could be useful to review these fundamental ideas. They are, in summary:

- A model is a purposeful *simplification* of a system for solving a particular *problem* (or category of problems).
- We use ABMs when we think it is important for a model to include the system's individuals and what they do.
- Modeling is a cycle of formulating a precise question; assembling hypotheses for key processes and structures; formulating the model by choosing appropriate scales, entities, state variables, processes, and parameters; implementing the model in a computer program; and analyzing, testing, and revising.

Understanding this modeling cycle is so important that a review of modeling practice (Schmolke et al. 2010) concluded that explicitly thinking about and documenting each step in the cycle is the primary way we can improve how models are developed and used. Schmolke et al. proposed a very useful format ("TRACE") for documenting the entire cycle of developing, implementing, and analyzing a model. TRACE has been further developed by Augusiak et al. (2014) and Grimm et al. (2014).

It is very important that you have a basic understanding of these ideas from the start, but for the rest of part I we focus on obtaining a fundamental knowledge of how to implement models on the computer. In the rest of this course, however, we will come back to modeling ideas. As soon as you have some ability to program and analyze your own models and some understanding of how to use these modeling concepts, you will rapidly become a real modeler.

1.6 Exercises

- 1. One famous example of how different models must be used to solve different problems in the same system is grocery store checkout queues. If you are a customer deciding which queue to enter, how would you model the problem? What exact question would your model address? What entities and processes would be in the model? Now, if instead you are a store manager deciding how to operate the queues for the next hour or so, what questions would your model address and what would it look like? Finally, if you are a store designer and the question is how to design the checkout area so that 100 customers can check out per hour with the fewest employees, what things would you model? (Hint: Think about queues in places other than stores.)
- 2. For the following questions, what should be in a model? What kinds of things should be represented, what variables should those things have to represent their essential characteristics, and what processes that change things should be in the model? Should the model be agent-based? If the question is not clear enough to decide, then reformulate the question to produce one that is sufficiently clear.
 - a) How closely together should a farmer plant the trees in a fruit orchard?
 - b) How much of her savings should an employee put in each of the five investment funds in her retirement program?
 - c) Should a new road have one, two, or three lanes in each direction?
 - d) Is it acceptable to allow a small legal harvest of whales?
 - e) To complete a bachelor's degree in physics as soon as possible, what classes should a student register for this semester?
 - f) How many trees per year should a timber company harvest?
 - g) Banks make money by investing the money that their customers deposit, but they must also keep some money available as cash. A bank can fail if its customers withdraw more cash than the bank has available, or if their investments do not make enough money to meet expenses. Government regulators require banks to keep a minimum percentage of total deposits as cash that is not invested. To minimize bank failures, what should this minimum percentage be?
 - h) To maximize profit, how many flights per day should Saxon Airlines schedule between Frankfurt (their international hub) and Leipzig?
 - i) To minimize system-wide delays and risk of accidents, how many flights per day should the European Aviation Administration allow between Frankfurt and Leipzig?
 - j) Two new movies will open in theaters next weekend. One is based on a comic book series and features a superhero, special effects, car chases, and violence. The other is a romantic comedy starring a beautiful actress and a goofy but lovable actor. Which movie will make the most money next weekend? Over the next four weeks? Over the next five years?
 - k) Using your own studies, research, or experience in general, what other problems or questions might be the basis of a model or agent-based model?

Index

- actions (elements of a model schedule), 41, 190–199 adaptation and adaptive behavior, 10, 41–42,
 - 149–150; evolutionary approaches, 320; memory in, 182–85; modeling of, 154–59; non-optimizing approaches and satisficing, 155–56; prediction in, 161–64, 169; optimization approaches, 150–53; rule-based approaches, 210; stay-or-leave decisions, 256; stochastic approaches, 210–11; theory for, 249–55, 319–20; with trade-offs among objectives, 150, 154–55, 251–52

Agent Monitors, 26–27, 80, 84, 122, 153 agent-based models: across-level nature of, 10; and theory, 249–55, 319–20; criticisms of, 91, 275; definition of, 10–12; difference between individual-based models and, xii; full-fledged,

11–12; typical questions of, 11 agents: decision alternatives as, 150–52; definition of, 10; NetLogo terminology for, 16–17

agentsets: built-in, 31, 150–51; differences between lists and, 183; initialization of, 112; local, 151; merging of, 140–41; for modeling collectives, 216, 218, 223; removing agents from, 141; sensing of, 135, 139–40; sorting, 192–93;

subsetting (filtering) of, 150–52 alternatives analysis and model uncertainty, 310–12 and, 93, 152

anonymous procedures, 184, 193 arithmetic operators, 26 ask: and changes in code context, 18, 53; randomization by, 183, 190; used to make agents execute code, 21; used to set variables of other agents, 135–36

attributes. See state variables

basic principles (element of ODD model description protocol), 42

Bayesian updating theory to model prediction, 169 beech forest model BEFORE, 241–45

beginners' mistakes and difficulties, 8, 9, 22, 39, 66, 68, 319

behavior. See adaptation and adaptive behavior

BehaviorSpace, 105–11, 154; in calibration experiments, 271, 273–74; on computer clusters, 322; global variables for, 133; and the go procedure's organization, 192; random number control and, 209, 299–301; for sensitivity and uncertainty analysis, 302, 309–10; using without putting variables on the interface, 302; for writing output, 128

Bernoulli distribution, 206-7

boolean conditions, reporters, and variables, 25, 66, 185, 212; generated by a Bernoulli distribution, 200–201; in if and ifelse statements, 25, 185; in looping, 196; controlled by switches on Interface tab, 66, 93

brainteasers, 54, 114, 152

Breeding Synchrony model, 194; robustness analysis of, 313

breeds, breed, and breeds-own, 215, 217-18, 222-25

- Business Investor model: adaptive behavior in, 154–55; empirical model of behavior in, 210–11; with links for sensing a network, 144–45; objective function in, 158–59, 164– 68; ODD description of, 137–39; prediction in, 162–64
- Butterfly Hilltopping model: analysis of, 69; emergence in, 103–4; implementation in NetLogo of, 50–59, 64–68, 69–74; observation of, 121–22; ODD description of, 43–46; real landscape data imported for, 71–74; testing software of, 87–91
- buttons: context of, 18; creation of on Interface, 19–20, 53, 55; Forever button, 20, 55; selecting and modifying, 55; step button, 83; for test and display procedures, 85, 122. *See also* syntax errors and checker
- calibration and parameterization: automated, 321; categorical vs. best-fit, 267; criteria for, 269–70; definition and purposes of, 263–64; and differences between traditional modeling and ABMs, 264–65; documentation of, 276; literature on, 266; measures of model fit for, 268–70; overfitting in, 266, 272; parameters for, 266–67, 294; purposes of, 264; statistics for, 295–96; strategies for, 266–64; with stochastic results, 271; of submodels, 43, 265–66; and theory testing, 263–64; time-series, 268–69
- carefully, 126-27
- checklist: of design concepts, 41–42; of NetLogo elements, 30–31
- clear-all, 22; and BehaviorSpace, 109, 302; variables on Interface not set to zero by, 66
- Code Examples in NetLogo Models Library, 16, 69, 125–26, 208
- collectives (model design concept), 41–42; definition of, 215; as emergent properties vs. explicit entities, 215; represented via breeds, 217–18; represented via patches or links, 216–17; Wild Dog Model example, 219–227; Woodhoopoe Model example, 257
- comma-separated values (.csv) files, 71, 125–28; CSV extension to write, 125; and European computers, 71, 126; produced by export primitives, 70, 128
- Command Center, 26-27, 83, 85
- comments in code, 57–59, 60; for temporarily deactivating code, 58, 66, 92, 293, 302; in version control, 64

- communication of models and science, 10, 35, 260, 300
- competition, 139, 173, 174; in the BEFORE forest model, 241, 243–44; and scheduling model actions, 186, 192–94, in the Telemarketer Model, 176–77, 180, 194; in the Wild Dog Model, 218, 221
- conceptual framework for agent-based modeling, 41–42, 99–100
- contexts in NetLogo programming, 17–18, 53, 57–58, 79, 81, 134, 136, 142; and breeds, 217; and foreach, 193; using local variables in multiple contexts, 74
- continuous time simulation. See discrete event simulation
- contour plots: in calibration, 273; using Excel, 164–66; of parameter interactions in sensitivity analysis, 304–6; in submodel analysis, 164–68; using R, 166–67
- Cooperation model, 174
- copying of code: benefits and ethics of, 125–26; as cause of errors, 78–79
- count, 27, 67, 196
- create-link(s)-to, 144, 182, 224, 227
- create-turtles (crt), 23, 54; and breeds, 217; context started by, 18; and initialization of turtle variables, 23, 144; order of creation vs. initialization in, 144
- csv files. See comma-separated values files
- currencies of model results, 292–93; in sensitivity analysis, 301, 306
- debugging of code. *See under* software decision-making traits. *See* adaptation and adaptive behavior deduced variables, 39, 245 defensive programming, 205–7, 224, 309 design concepts: as a conceptual framework, 99–100;
- in ODD protocol, 41–42
- detective work in modeling, 78, 95, 246, 295, 296, 312–13
- dictionary of NetLogo primitives, 17, 22; F1 key to access, 21–22
- discrete event simulation, 189, 194–98, 322 display, 121
- display. See Interface tab in NetLogo; View distance, 114
- distance to nearest other agent set by, 114–15, 153 documentation: of analyses, 171, 238, 282; of soft-
- ware tests, 58, 91–92. *See also* ODD protocol for model description; TRACE format for describing a modeling cycle

334

emergence (model design concept), 10, 42, 103–4, 116; of collectives, 216; criteria for, 103; in

Flocking model, 111–12

entities: collectives as, 215–18; in ODD protocol, 38–39; selection of, 9, 239–40

environment: emergence from, 103-4, 116, 173;

modeling of, 17, 38-39, 40, 43, 133, 194, 321

epidemic models, 315–16; for rabies 3–4

error-message, 126-27

evolutionary modeling of behavior, 320 Excel spreadsheet software, 126, 164–66, 273

- execution speed, 109, 321–22. *See also* speed controller
- export- primitives, 70-71, 128

extensions to NetLogo, 208–9, 320–21; CSV, 125; GIS, 71, 320; Networks, 173; R, 209, 321

- extinction: risk of in Wild Dog model, 218, 228, 296, 302–5, 310–12; in the Simple Birth Rates model, 105–10
- false. See boolean conditions, reporters, and variables

file- primitives, 72, 87-88, 125-28

files: input, 43, 72; output, 88, 124–28; problems with due to multiple processors and BehaviorSpace, 109–10; for software testing, 87–88, 89–90. *See also* BehaviorSpace; comma-separated values files; export – primitives

filter,184

filtering agentsets, 151

fitness, 41, 42, 45, 149–50, 256, 258. See also objectives

Flocking model: analysis of using BehaviorSpace, 112–15; calibration exercise with, 278; collectives in, 216; emergence in, 111, 116; related scientific models, 112, 216, 253

foreach, 86, 139, 193

forest model. See beech forest model BEFORE

forward (fd), 25-26

fput, 86, 184

Geographical Information Systems (GIS) extension for NetLogo, 320, 322

global variables, 17, 18, 132–33; and clear-all, 22; controlling in BehaviorSpace, 107, 109; defining of, 23, 50; initialization of, 56, 67; movement to Interface of, 66; and the observer, 17; risks of using, 133; typical uses of, 17, 133

globals, 23, 50, 132; and variables on Interface, 66

go procedure, 18, 19, 21, 23–24, 190–92; and BehaviorSpace, 109, 192; as the model schedule, 23–24, 50, 190–92; number of times executed, 27, 55, 109; value of keeping simple, 24, 48, 124

hatch, 18, 27, 134, 217, 224

header information in output files, 125–27 help sources, 29, 33, 64. *See also* instructors' guidance

heuristic models of behavior, 258, 319, 320

heuristics for developing and analyzing models, 9, 286–95, 296

-analyze simplified versions of your model, 293

-analyze from the bottom up, 294

 —at an interesting point in parameter space, keep the controlling parameter constant and vary other parameters, 290

-explore unrealistic scenarios, 294

-find "tipping points" in model behavior, 288

- —look for striking or strange patterns in the model output, 290
- -run the model step by step, 289
- -try different visual representations of the model entities, 289
- -try extreme values of parameters, 288

—use several "currencies" for evaluating your simulation experiments, 292

- hierarchies among agents, representing via scheduling, 192
- Hilltopping Butterfly model. See Butterfly Hilltopping model
- histogram and histograms, 123-24, 178, 257, 311

hypothesis testing: in model analysis, 282, 285, 286–95; in software testing, 87; for theory development, 237, 250–55

ifelse and ifelse-value, 24-25, 55-56, 82, 134-35, 185

in-cone, 151

in-radius, 21-22, 79-80, 142-43, 151-53

individual-based ecology, xii, 9

individual-based models. See agent-based models

initialization, 18–19, 22, 43; and BehaviorSpace, 109, 302; of an empty agentset using noturtles, 112; via the Interface, 66; of lists, 183–84; using nobody to designate a turtle, 181; via the setup procedure, 19, 50, 52;

stochastic, 202, 209; of variables, 56, 67

input data, 43, 50, 320–21. See also files

instructors' guidance, xiv-xvi

interaction: between agent and environment, 42, 59, 61; among agents, 42, 173–74; direct vs. mediated, 173; local vs. global, 12, 173, 174–75, 294;

interaction (continued) among model processes, 290, 295; parameter, 303-5, 306-7; programming of long-term, 181-82; among system levels, 10 Interface tab in NetLogo: addition and modification of elements in, 19-20, 53, 55, 123-24; and clear-all, 22, 66; hiding code in, 70, 107-8, 122; input, 129; monitor, 119; movement of variables to, 66; observer context of, 18, 132-33; output, 68, 119. See also Agent Monitors; Command Center; Model Settings dialog; plots; speed controller on NetLogo Interface; View internal organization of systems, 233-35, 242-45 label and plabel, 61, 83, 120-22 landscapes. See spaces and landscapes learning (model design concept), 42, 98, 259 length, 184 let. See local variables link-neighbors primitives, 144-45, 151, 182, 223-26 links in NetLogo, 17, 134, 144-45, 173, 181-82; for associating collectives with their members, 223-27; for representing collectives, 216-17 links-own,134 lists: arrays and tables as alternatives to, 208; definition and initialization of, 85, 183-84; in calculating statistics, 135; for modeling memory, 85-86, 183-84; produced from an agentset by of, 135; sorting of, 193 local randomness, 209-10, 309-10 local variables: containing agentsets, 93, 151; created by let, 67; defined, 134-35; and inputs to reporters, 141; reasons for using, 73-74, 134-35, 136 log-normal distribution, 206, 214 logistic functions, 220, 221-22 logistic regression, 203, 212 loop, 196-97 loops: in NetLogo, 196-97, 205-6, 309; vs. Net-Logo's style, 29, 139-40 management accounting and collusion models, 245 - 46management applications of models, 3-4, 38, 218-19, 227-28; and model uncertainty and robustness, 310-12, 314 market models, 11, 40, 253-54 Mathematica, 162, 321 max and min, 73, 124, 135 max-n-of and min-n-of, 151

max-one-of and min-one-of, 114-15, 141, 152, 153 max-pxcor and max-pycor, 16, 18, 51, 80 mean, 17, 68, 123, 128, 135, 217 memory, models of, 85-86, 182-85 model, definition of, 4-7 model fit measures, 265, 266, 267-69, 271 Model Settings dialog, 18, 51-52, 72; errors caused by, 80 modeling cycle, 7-12, 37, 63, 119, 238, 250-51, 281, 318-19; TRACE format for documenting, 12, 43, 91, 238, 282 Models Library of NetLogo, 16, 63, 125-26, 208, 318; limitations of, 63, 318 modular code, 141 monitors. See Agent Monitors Mousetrap model, 194-98 move-to, 17, 26, 54-56 multiagent systems, xii multicriteria assessment of models, 234 Mushroom Hunt model: as calibration exercise, 278; as example modeling problem, 5-10; as introductory programming example, 18-28; as modeling cycle example, 7–9; as searching behavior example, 157 myself, 93, 114-15, 136, 141-42, 152-53, 175 n-of, 21-22 nearest other agent, 114-15, 152-53 neighbors, 17, 80, 87, 90, 93, 140, 143 NetLogo: checklist and mini-reference, 30-31; extensions, 73, 125, 173, 195, 208-9, 320-21; influence of on model and research design, 30; installation, 16; introduction to, 16-18; ODD protocol correspondence with, 49-50; personality and style of, 29; suitability for large models and alternatives to, xiii-xiv, 313-15; terminology, 17-18; Users Group, 33; versions, xvi, 16; why to use, xiii-xiv networks: in the Business Investor model, 144-45; in the Models Library, 173; representing in NetLogo, 144-45, 208, 217 neural network models of behavior, 320 nonspatial models, 110, 180, 220, 229, 294 null submodels and theory, 252, 254, 255, 319 objectives (model design concept), 41-42, 149-50; in the Business Investor model, 154; in the Woodhoopoe model, 258-59 objectives of this book, xii-xiii

pattern-oriented modeling, 240; of NetLogo models, 120–28

observer and observer context in NetLogo, 17–18, 50, 132–33

ODD protocol for model description, 35–43; and standardization of terminology, xii; and corresponding elements in NetLogo, 49–50; and design of models, 36, 99–100; template document for, 37

--of the BEFORE beech forest model, 242-44 --of the Breeding Synchrony model, 74-75 --of the Business Investor model, 137-39

-of the Butterfly Hilltopping model, 43–45 -of the Culture Dissemination model, 90–91

—of the Harvester model, 96

-of the Segregation model, 286–87

----of the Telemarketer model, 175-79

—of the Wild Dog model, 219–21

-of the Woodhoopoe model, 257-59

of, 18, 135-36, 175

one-of, 54; agentset converted to an individual agent by, 182

or, 152

other, 113-15, 144, 151-53

output. See files; Interface tab in NetLogo; observation

overfitting in calibration, 266, 272, 276

panic, when not to, 9, 18, 275. See also worry parameters: definition of, 23, 39; documentation of, 43; estimating values of, 263-72; as global variables and on the Interface, 23, 66, 133; interaction among, 304-7; for logistic functions, 221-22; model sensitivity to, 104, 299-300, 301-7; model uncertainty due to, 264, 307-12; parameter space, 271; of random number distributions, 202, 205-9, 212, 219; reference (standard) values of, 301, 302; World settings as, 18, 51-52, 80, 146; See also calibration and parameterization patch, 72-73 patch-here, 67, 85-86, 140-41, 152-53 patch-set, 140-41 patches-own, 50, 51, 133 pattern-oriented modeling, 233-35, 239-41, 249-52, 263-64

patterns: characterization of system and problem by, 234–36; criteria for matching, 236, 260–61, 269–70; in software testing, 82–83 pen-down and pen-mode, 27 plabel, 83, 121–22 plot, 70, 123 plots, 69-70, 123-24; export of, 70-71, 128. See also contour plots Poisson distribution, 169, 207-8, 212, 221 positive feedbacks, 192 precision, 83, 121, 124 prediction (model design concept), 42, 161-64, 169-70 predictions from models: absolute vs. relative, 311-12; independent or secondary, 244-45 primitives, 17; errors due to misunderstanding of, 79-80; provided by extensions, 320 probability: Bayesian updating of, 169-70; logistic model of, 220-22; in objectives for adaptive behavior, 159, 168, 252; observed frequencies as, 202-3, 210-11; and parameters in sensitivity analysis, 301-2, 304; in prediction, 169-70, 171; random distributions and theory of, 204-8; in software testing, 87 problem addressed by a model. See question addressed by a model processes in a model: description of, 40-41, 43; design of, 7-9, 39, 233-34, 239, 240-41, 249-252, existing models of, 320-21 programming practices, 57-59, 60, 64-65, 67, 68-69,

77–78, 81–82, 86, 91–92, 94–95, 125–26, 205 pseudocode, 41 pseudorandom numbers, 204

question (problem, purpose) addressed by a model, 4-7, 11, 38, 233-34, 318-19

R statistical software, 89, 162, 166, 209, 306, 321 rabies control models, 3-4 random, 24-25, 207 random-float, 55-56, 205 random-normal, 204, 205-6; converted to lognormal distribution, 214 random number distributions, 202-8 random number generation and seeds, 209-10; and BehaviorSpace, 209-10; use of in uncertainty analysis, 309-10 random-poisson, 207-8 random-seed. See random number generation and seeds regimes of control, 288 reimplementation: of existing models, 318-19; of submodels to test software, 89-91 repeat, 196 replication and repetitions, 105-7, 115, 203; in

calibration, 271; and random-seed, 209; in sensitivity analysis, 302; in statistical analysis of results, 295

reporters, 17, 67, 141-42, 175; in BehaviorSpace and Interface elements, 107, 128, 273; as boolean logical conditions, 185 reset-ticks, 27, 191-92 resize-world, 72, 80 right, 25 robustness analysis, 299-300, 312-13 run-time errors, 80, 322. See also defensive programming

satisficing decision traits, 155–58 scale selection, xiii, 9, 39–40, 174, 191, 233, 265. *See also* pattern-oriented modeling; scheduling scale-color, 52–53, 83, 120, 122–23 scenarios in simulation experiments, 106–7; contrast of, 115, 295; and uncertainty analysis, 310–12; usefulness of unrealistic, 59, 294–95, 313 scheduling, 23, 40–41, 189–92; discrete event, 194–98; and the go procedure, 50; to represent hierarchies, 192–93; using time steps, 190–92; of View and observer actions, 121 science and agent-based modeling, xii–xiii, 9–10, 36, 63, 77, 86, 99, 112, 149, 234, 250, 319–20

scientific method. *See* strong inference and scientific method

- scope of variables, 132-35
- Segregation model, 286-91, 314
- sensing (model design concept), 42, 131–32, 136–37; of an agentset, 139–40; in networks of links, 144–45
- sensitivity analysis, 267, 300, 314, 321, 322; global, 306–7; parameter interactions in, 304–6; single-parameter, 301–4
- sensitivity experiments, 106, 116, 227-28, 288, 313 set, 21
- set-current-plot,124
- Settings, Model. See Model Settings dialog
- setup procedure, 19–24, 52–54, 71–74, 126; interaction of BehaviorSpace with, 109, 112, 302; and initialization element of ODD, 50, 52; and variables on Interface, 66. See also initialization show, 26–27, 58, 69, 83, 153
- Simple Birth Rates model, 104–11
- simulation experiments, 65, 251, 285, 296, 318; examples of, 65–69, 104–11, 112–15, 142–43, 154–55, 162–64, 179, 227–28; replication of, 203. *See also* calibration and parameterization; robustness analysis; sensitivity analysis; theory; uncertainty analysis

skeletons of procedures, 21, 52, 60, 81–82 sliders, 55, 66, 133; and BehaviorSpace, 107, 109 software: alternatives to NetLogo, xiii–xiv, 321–22; common errors in, 78–81; testing and

verification of, 81-91. See also programming practices sort-on, 193 spaces and landscapes, 38-40; benefits of simplifying, 59, 293, 313; in the Business Investor model, 137; in the Butterfly model, 44, 51-53, 71-74; from imported data, 72-73, 320; of irregular polygons, 322; non-geographic, 10, 74, 137, 173; scales of, 39-40; wrapping, 22, 80 spatial extent, 40, 51-52 speed controller (slider) on NetLogo Interface, 26, 83, 121, 192 spreadsheets: for preparing input and analyzing results, 71, 72, 109-10, 273; for reimplementing submodels, 87-91; to test and explore submodels, 162, 164-67, 170 stability properties, 293 standardization of agent-based modeling, xiii, 36 state variables, 9, 38-39, 43. See also variables statistical analysis: for software testing, 87-88, 95; of model results, 203, 295-96, 306, 321 stochasticity (model design concept), 42, 201-3; analysis of via replication, 203; in calibration, 271; in models of behavior, 210-11, 219; and sensitivity analysis, 301-3; in uncertainty analysis, 307; uses of, 202-3 stop, 55, 68, 109; in looping, 196 Stopping rules and stopping models, 55, 198; in BehaviorSpace, 107-8, 109 strong inference and scientific method, 234, 250 structure and structural realism of models, 7-9, 38-40, 233-34, 239-40, 264 stylized facts, 234 submodels: behavior submodels, 149; and corresponding procedures in NetLogo, 50; definition of, 40, 43; description of in ODD protocol, 43; implementation and analysis of, 164-70, 171, 294; independent reimplementation of, 89-91; parameterization of, 265-66 syntax errors and checker, 20, 78, 79, 81-82

Telemarketer model: analysis of, 179; addition of mergers to, 180–82; collectives in, 216; with customers remembering callers, 182–85; ODD description of, 175–79; potential bias in due to execution order, 186, 192, 194

temporal extent, 39-40, 55, 198

- testing software. See under software
- theory in agent-based models: definition of, 249–50; development and testing of, 250–52, 319–20; examples of, 252–55

theory potentially useful in adaptive traits: Bayesian updating of probabilities, 169–70;

evolutionary modeling, 320; game theory, 245-46; objective optimization in decision analysis and behavioral ecology, 154, 251-52; probability, 169, 204; satisficing, 155-58; simple heuristics, 319-20; state- and prediction-based theory, 252 tick and ticks, 27, 55, 107, 121, 191-92; and BehaviorSpace, 107 tick-advance and non-integer ticks, 195-96 time in models. See scheduling time steps, 39-40, 190; consequences of using, 191-92. See also scheduling; tick topology of NetLogo's world, 22. See also Model Settings dialog to-report, 67, 141-42 TRACE format for describing a modeling cycle, 12, 43, 91, 171, 238, 276 trade-off decisions, 150, 154-55, 162-64, 251-52 troubleshooting tips, 68-69 true. See boolean conditions, reporters, and variables turtles-here, 121-22, 134, 140, 143, 151; to identify members of a patch collective, 216 turtles-on, 79-80, 151 turtles-own, 25, 50, 134, 217 uncertainty: in calibration data, 270; not quantified by replication, 203; reduction of via calibra-

b) repleation, 205, reduction of via canona tion, 260, 266; in sensing information, 131; structural vs. parameter, 264; and theory development, 260
uncertainty analysis: definition of, 300; methods for, 307–312; of relative vs. absolute predictions, 310–12
underdetermined models, 239
uphill, 17, 56, 91
User Manual for NetLogo, 15–17, 26
user-file, 72

utility (economic objective), 41; and Business Investor model, 138, 149–50, 154–59, 164–68

validation of models, 244–45. *See also* patternoriented modeling; theory in agent-based models variables: of breeds, 217; built-in, 17, 23, 51, 120; choosing (*see* structure and structural realism of models); that contain agents and agentsets,

67; discrete vs. continuous, 26; local, 67, 73–74; names of, 58, 86; of other objects, 135–36; scope of, 132–35; types of, 17, 51. *See also* state variables

version control, 64–65

View, 120–23; changing size of, 52; in continuoustime models, 197–98; updating of, 121, 191–92. See also Interface tab in NetLogo

wait,121

website for this book, xvi

while, 72, 196–97; to catch normal distribution outliers, 205–6, 309

Wild Dog model, 218–28; ODD description of, 219–21; sensitivity analysis of, 302–4, 304–6; uncertainty analysis of, 307–11

with, 67, 141, 151-52

with-local-randomness, 209-10, 212, 309-100

with-max and with-min, 114-15, 151, 152-53

Woodhoopoe model: calibration of, 272–75; ODD description of, 257–59; as theory development exercise, 256–59, 260–61

word, 70, 83; example uses of in error statements, 207, 225; to produce .csv output files, 127; to produce output files from BehaviorSpace experiments, 110

world and wrapping, 22, 80. See also Model Settings dialog

worry, why not to yet, 41, 47, 64, 94, 112, 145, 270. *See also* panic

Index of Programming Notes

A simple way to import spatial data, 72–73 A very brief introduction to output files, 88 Ask-concurrent, 193–94 BehaviorSpace, multiple processors, and output files, 109–10 Clear-all, 22 Copying code, 125–26 CSV files, 71 How BehaviorSpace works, 109 Logical conditions are reporters, 185 Modifying Interface elements, 55 Moving variables to the Interface, 66 Numerical recipes and NetLogo extensions—don't reinvent the wheel again!, 208–9 Parameterizing and programming logistic function, 221–22 Shortcut keys for editing, 20 Sensing the members of an agentset, 139–40 Tracking relationships and long-term interactions via variables and via links, 181–82 Troubleshooting tips, 68–69

Updating display variables to represent agent states,	Using -set to merge agentsets, 140-41
122–23	Version control, 64-65
Using repeat, loop, and while to execute code	When is the View updated?, 121
repeatedly, 196–97	Writing reporters, 141-42